

$$E(\underline{Y} | \underline{z}) = E(\underline{Y}) + C_{yz} C_{zz}^{-1} (\underline{z} - E(\underline{z})) \rightarrow M$$

①

- optimal for jointly Gaussian RVs  $(\underline{Y}, \underline{z})$

- linear estimator  $\sim M \cdot (\underline{z} - E(\underline{z}))$

- Complexity (computational) is finding  $C_{zz}^{-1}$

linear estimator :  $\Leftrightarrow$  Gaussian  $E[\underline{Y} | \underline{z}]$

①

↓

$$\hat{\theta} = \sum_{i=1}^n a_i x_i + b \rightarrow \text{Bias } \neq 0$$

Scalor

$$E((\hat{\theta} - \theta)^2) = E\left(\left(\sum_{i=1}^n a_i x_i + b - \theta\right)^2\right)$$

$$\frac{d}{db} (\ ) = \cancel{E((\hat{\theta} - \theta))} \cdot \frac{d}{db} \hat{\theta} = 1 = 0$$

$$= E\left(\underbrace{\sum_{i=1}^n a_i x_i + b}_{\hat{\theta}} - \underbrace{\theta}_{\theta}\right) = 0$$

$$b = E[\theta] - \sum_{i=1}^n a_i E[x_i] \rightarrow 0$$

Find coefficients via

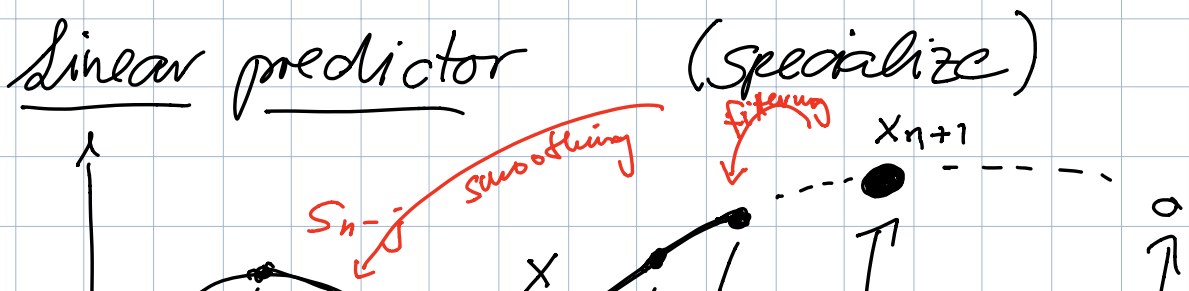
$$\frac{\partial}{\partial a_i} E((\hat{\theta} - \theta)^2) = \frac{\partial}{\partial a_i} E[(\hat{\theta} - \theta) \cdot \frac{\partial \hat{\theta}}{\partial a_i}] = 0$$

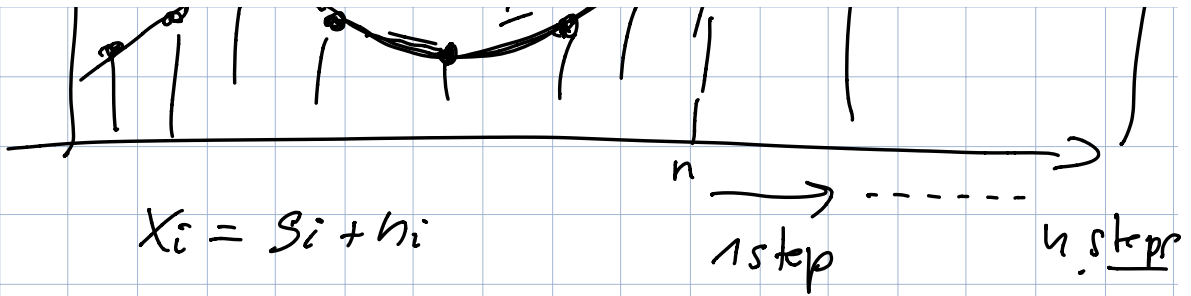
$$= E\left[\underbrace{\left(\sum_{i=1}^n a_i x_i + b - \theta\right)}_{\hat{\theta} - \theta} \cdot \underbrace{x_i}_{\text{data}}\right] = 0$$

estimator error

$$E[e \cdot x_i] = 0$$

orthogonality principle





1)  $\Theta = X_{n+1}$

$f_{X_{n+1}, \underline{x}}$   $\rightarrow$   $f(\Theta, \underline{x})$

~~$\Theta$~~

2)  $\Theta$  changes with  $n \Rightarrow$  dynamic

OP:

$$E\left(\hat{X}_{n+1} - X_{n+1}\right) \cdot \underline{x} = \underline{0}$$

predictor order  $\swarrow$

$$E\left(\sum_{i=0}^{N-1} a_i X_{n-i} - X_{n+1}\right) \cdot X_i = 0$$

$N$  unknowns  $\uparrow$

$i = n - N + 1, n$

$$\underline{a} = R^{-1} \cdot \underline{v}$$

$$R_{ij} = E[X_i X_j]$$

$$X_i = a + h_i$$

$$X_i = S_i + h_i$$

$$\begin{bmatrix} R_{nn} & R_{n,n-1} & \dots & \dots \end{bmatrix}$$

$$\underline{R} = \begin{bmatrix} R_{n,n} & R_{n,n-1} & \dots & \dots \\ \vdots & \vdots & \ddots & \vdots \\ \vdots & \vdots & \ddots & \vdots \\ \vdots & \vdots & \dots & R_{n-N+1, n-N+1} \end{bmatrix} \quad E[X_i X_j] \quad n-N+1 \leq i, j \leq n$$

$$\underline{v} = [R_{n+1, n} \quad R_{n+1, n-1} \quad \dots \quad R_{n+1, n-N+1}]$$

$E[X_{n+1} \cdot X_i]$

Assume a stationary process:

$$\begin{aligned} E[X_i X_j] &= E[X_{i+n} X_{j+n}] \\ &= E[X_i X_{i+(j-i)}] \\ &= E[X_i X_{i+\Delta}] \end{aligned}$$

$R_\Delta$

Wiener-Hopf Equations:

$$\underline{a} = R^{-1} \cdot \underline{v}$$

avoid at all cost!

$$\underline{R} \underline{a} = \underline{v}$$

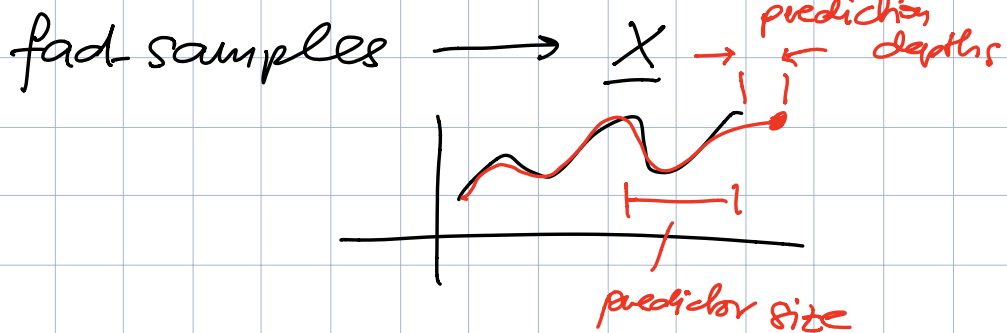
$$\begin{bmatrix} R_0 & R_1 & \dots & R_{N-1} \\ R_1 & R_0 & R_1 & \dots \\ R_2 & R_1 & R_0 & R_1 \dots \end{bmatrix} \cdot \underline{a} = \begin{bmatrix} R_1 \\ R_2 \\ \vdots \end{bmatrix}$$

$$\left[ \begin{array}{c} R_{N-1} \dots R_0 \end{array} \right] \quad \left[ R_N \right]$$

Levinson-Durbin Algorithm ??

complexity of  $R^{-1} \sim O(N^3)$

Linear Predictor, m



How do we find

$$R_\Delta = E[X_i X_{i+\Delta}] = ?$$

1) assume process stationary

2) sample correlation

$$R_\Delta \approx \frac{1}{L} \sum_{i=0}^{L-1} X_i X_{i+\Delta} = \hat{R}_\Delta$$

learning phase

Theory!

practice

Wiener-Hopf

$$\Rightarrow a$$

$$\Rightarrow \hat{X}_{n+1} = \sum_{i=0}^{N-1} a_i X_{n-i}$$

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